

# Robosavvy Tugbot - Collaborative Mobile Robot

### **Technical Specifications**



Application

Product type Collaborative autonomous mobile robot for transport of payloads

and/or tow wheeled carts

**Physical characteristics** 

Dimensions  $741 \times 640 \times 463 \text{ mm [LxWxH]}$ 

Weight 47kg (standard configuration)

**Performance** 

Operational time 5h continuous

Max Pull Force 300Kg (depends of floor surface)

Max payload 70kg (carry on payload)

Max Speed 2.0m/s

Max Incline 5°

Turning radius 0.3m (without cart)

Position accuracy +/-5cm; +/-1cm with 2D code marker

**Environmental conditions** 

Max traversable gap 3cm

Floor Flat ground with smooth surface

Environment type Indoor

Ambient temperature range -5°C to 50°C (humidity 10-95% non-condensing)

IP class IP 30

Connectivity

Wi-fi 802.11a/b/g/n/ac, 2.4/5 GHz Dual-Band

Bluetooth 4.0 LE

Sensors

Front Lidar Hokuyo UAM-05LP-T301 – Safety compliant ISO13849-1,

IEC61496-1/3

Rear Lidar Hokuyo URG-04lx

Front camera RGB / 3D depth camera
Rear camera RGB / 3D depth camera

**Power** 

Battery (wheels) Li-lon 55V/650Wh
Battery (sensors and control) Li-lon 12V/240Wh

## **TUGBOT 1.0** Datasheet



Charging time 2h30 to full charge

Battery charger External (docking station)

Safety / Warnings

Emergency stop Safety lidar and emergency stop button

Warning light Flashing orange light

Warning sound Buzzer
Status lights RGB Leds

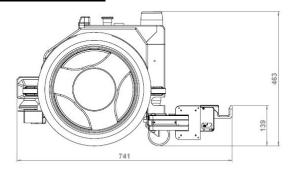
**Attachments** 

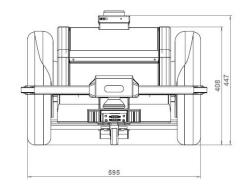
Tow hook Customizable gripper for towing metal carts / wheeled pallets

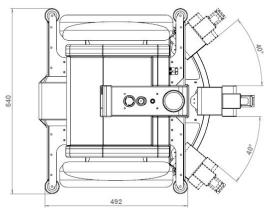
Top tray

Customizable top tray to carry payload

### **TUGBOT 1.0 dimensions**







# Robosavvy Ltd

UK

61-63 Rochester Place London NW1 9JU, United Kingdom +44 207 183 7505

#### www.robosavvy.com

info@robosavvy.com

## Portugal

Rua Alex O'Neil, Vila Inter ED1 RC2 2750-047 Cascais, Portugal +351 214 852 548

